姓名: SOLUTION

學號:

Quiz 16

考試日期: 2023/06/14

1. 請框出答案. 2. 不可使用手機、計算器,禁止作弊!

1. Find a Jordan canonical form and a Jordan basis for the matrix A

$$A = \begin{bmatrix} i & 0 & 0 & 0 & 0 \\ 0 & i & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 \\ 2 & 0 & -1 & 0 & 2 \end{bmatrix}$$

Solution:

It is easy to find that the A has the eigenvalue i, whose algebraic multiplicity is 2 and A has the eigenvalue 2, whose algebraic multiplicity is 3.

From above, we know that

$$(A - iI) : \vec{b}_1 \to \vec{0}$$
$$\vec{b}_2 \to \vec{0}$$

Thus, pick $\vec{b}_1 = \vec{e}_2$, and $\vec{b}_2 = \begin{bmatrix} -2+i \\ 0 \\ 0 \\ 0 \\ 2 \end{bmatrix}$.

From above, we know that $\begin{array}{ccc} (A-2I):\vec{b}_4 \rightarrow & \vec{b}_3 \rightarrow \vec{0} \\ \vec{b}_5 \rightarrow \vec{0} \end{array} \text{ and } \begin{array}{c} sp(\vec{e}_4,\vec{e}_5) = sp(\vec{b}_3,\vec{b}_5) \\ sp(\vec{e}_4,\vec{e}_5,\vec{e}_3) = sp(\vec{b}_3,\vec{b}_5,\vec{b}_4) \end{array}$ Since $\vec{b}_4 \in null((A-2I)^2)$ and $\vec{b}_4 \notin null(A-2I)$, we can pick $\vec{b}_4 = \vec{e}_3$.

Since $\vec{b}_4 \in null((A-2I)^2)$ and $\vec{b}_4 \notin null(A-2I)$, we can pick $\vec{b}_4 = \vec{e}$ Let $\vec{b}_3 = (A - \lambda I)\vec{b}_4 = (A - 2I)\vec{e}_3 = -\vec{e}_5$. Since $\vec{b}_5 \in null(A-2I)$ and $\vec{b}_5 \neq \vec{b}_3$, we can pick $\vec{b}_5 = \vec{e}_4$.

$$V = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 & \vec{b}_3 & \vec{b}_4 & \vec{b}_5 \end{bmatrix} = \begin{bmatrix} 0 & -2+i & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 2 & -1 & 0 & 0 \end{bmatrix}, J = \begin{bmatrix} i & 0 & 0 & 0 & 0 \\ 0 & i & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 & 0 \\ 0 & 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix}, A = VJV^{-1}$$

2. Find a Jordan canonical form and a Jordan basis for the matrix A

$$A = \begin{bmatrix} 2 & 5 & 0 & 0 & -1 \\ 0 & 2 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix}$$

Solution :

It is easy to find that the A only has the eigenvalue 2, whose algebraic multiplicity is 5.

From above, we know that

$$(A-2I): \vec{b}_3 \to \vec{b}_2 \to \vec{b}_1 \to \vec{0} \qquad \text{and} \qquad \begin{aligned} sp(\vec{e}_1, \vec{e}_4) &= sp(\vec{b}_1, \vec{b}_4) \\ sp(\vec{e}_1, \vec{e}_4, \vec{e}_2, \vec{e}_5) &= sp(\vec{b}_1, \vec{b}_4, \vec{b}_2, \vec{b}_5) \\ sp(\vec{e}_1, \vec{e}_4, \vec{e}_2, \vec{e}_5, \vec{e}_3) &= sp(\vec{b}_1, \vec{b}_4, \vec{b}_2, \vec{b}_5, \vec{b}_3) \end{aligned}$$

Since $\vec{b}_3 \in null((A-2I)^3)$ and $\vec{b}_3 \notin null((A-2I)^2)$, we can pick $\vec{b}_3 = \vec{e}_3$. Let $\vec{b}_2 = (A - \lambda I)\vec{b}_3 = (A - 2I)\vec{e}_3 = \vec{e}_2$, and $\vec{b}_1 = (A - \lambda I)\vec{b}_2 = (A - 2I)\vec{e}_2 = 5\vec{e}_1$. Since $\vec{b}_5 \in null((A-2I)^2)$ and $\vec{b}_5 \notin null(A-2I)$ and $\vec{b}_5 \neq \vec{b}_3$, we can pick $\vec{b}_5 = \vec{e}_5$. Let $\vec{b}_1 = (A - \lambda I)\vec{b}_5 = (A - 2I)\vec{e}_5 = -\vec{e}_1 + \vec{e}_4$.

$$V = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 & \vec{b}_3 & \vec{b}_4 & \vec{b}_5 \end{bmatrix} = \begin{bmatrix} 5 & 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}, J = \begin{bmatrix} 2 & 1 & 0 & 0 & 0 \\ 0 & 2 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix}, A = VJV^{-1}$$