應數一線性代數 2021 春, 期中考試卷 A 解答

本次考試共有 9 頁 (包含封面),有 9 題。如有缺頁或漏題,請立刻告知監考人員。

考試須知:

- 請在第一及最後一頁填上姓名學號,並在每一頁的最上方屬名,避免釘書針斷裂後考卷遺失。
- 不可翻閱課本或筆記。
- 計算題請寫出計算過程,閱卷人員會視情況給予部份分數。
 沒有計算過程,就算回答正確答案也不會得到滿分。
 答卷請清楚乾淨,儘可能標記或是框出最終答案。

高師大校訓:**誠敬宏遠**

誠,一生動念都是誠實端正的。**敬**,就是對知識的認真尊重。 **宏**,開拓視界,恢宏心胸。**遠**,任重致遠,不畏艱難。

請尊重自己也尊重其他同學,考試時請勿東張西望交頭接耳。

1. (10 points) Let

$$A = \begin{bmatrix} -1 & 0 & 1 \\ -7 & 2 & 5 \\ 3 & 0 & 1 \end{bmatrix}$$

Find (if exists) an invertible matrix C and a diagonal matrix D such that $D = C^{-1}AC$. Also, find the eigenvalues of A^{100} .

- (1) Is A diagonalizable? No! If A diagonalizable, C =_____, D =_____.
- (2) The eigenvalue of A are <u>-2, 2, 2</u>. The eigenvalue of A^{100} are <u>2^{100}</u>.

Answer:

 $|A-\lambda I|=(2-\lambda)(\lambda^2-4),\,\lambda=-2,2,2$

$$A - 2I = \begin{bmatrix} -3 & 0 & 1 \\ -7 & 0 & 5 \\ 3 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} -3 & 0 & 1 \\ 0 & 0 & 8/3 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \vec{v} = \begin{bmatrix} 0 \\ s \\ 0 \end{bmatrix}, \text{ for } s \neq 0$$

Hence the algebra multiplicity of 2 is 2, but the geometry multiplicity of 2 is 1. Since they are NOT EQUAL, A is not diagonalizable.

2. (15 points) Find the formula for the linear transformation $T : \mathbb{R}^2 \to \mathbb{R}^2$ that reflects in the line x + 5y = 0.

Answer: $T([x, y]) = \frac{1}{13}[12x - 5y, -5x - 12y]$

Answer:

By the definition of "reflects in the line x + 5y = 0", we know T maps the vector [5, -1] onto [5, -1], and maps the vector [1, 5] onto [-1, -5]. Thus,

$$T([5, -1]) = [5, -1], T([1, 5]) = [-1, -5],$$

Let the s.m.r. of T is A, we got the eigenvalues of A are 1, -1, and the corresponding eigenvectors are $\begin{bmatrix} 5\\-1 \end{bmatrix}, \begin{bmatrix} 1\\5 \end{bmatrix}$ $A = \begin{bmatrix} 5 & 1\\-1 & 5 \end{bmatrix} \begin{bmatrix} 1 & 0\\0 & -1 \end{bmatrix} \begin{bmatrix} 5 & 1\\-1 & 5 \end{bmatrix}^{-1} = \frac{1}{13} \begin{bmatrix} 12 & -5\\-5 & -12 \end{bmatrix}$ $A * \begin{bmatrix} x\\y \end{bmatrix} = \frac{1}{13} \begin{bmatrix} 12x - 5y\\-5x - 12y \end{bmatrix}$

- 3. (15 points) (a) Solve the system $\begin{cases} x'_1 = 3x_1 + 2x_2 \\ x'_2 = x_1 + 2x_2 \end{cases}$ (b) Find the solution that satisfies the initial condition $x_1(0) = 2, x_2(0) = 5.$

 $\frac{\frac{14}{3}e^{4t} - \frac{8}{3}e^{t}}{\frac{7}{3}e^{4t} + \frac{8}{3}e^{t}}$ Answer: x_2 $A = \begin{bmatrix} 3 & 2 \\ 1 & 2 \end{bmatrix}$

Then the eigenvalues of A are 4, 1 and the corresponding eigenvectors are $\begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

$$\begin{bmatrix} 2 & -1 \\ 1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 3 & 2 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 0 \\ 0 & 1 \end{bmatrix}$$
$$\begin{cases} y_1' = 4y_1 \\ y_2' = y_2 \end{cases} \Rightarrow \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} k_1 e^{4t} \\ k_2 e^t \end{bmatrix}$$
$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} k_1 e^{4t} \\ k_2 e^t \end{bmatrix} = \begin{bmatrix} 2k_1 e^{4t} - k_2 e^t \\ k_1 e^{4t} + k_2 e^t \end{bmatrix}$$

Since

$$\begin{bmatrix} 2\\5 \end{bmatrix} = \begin{bmatrix} x_1(0)\\x_2(0) \end{bmatrix} = \begin{bmatrix} 2k_1e^0 - k_2e^0\\k_1e^0 + k_2e^0 \end{bmatrix} \Rightarrow \begin{cases} k_1 = \frac{7}{3}\\k_2 = \frac{8}{3} \end{cases}$$

Hence

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} \frac{14}{3}e^{4t} - \frac{8}{3}e^t \\ \frac{7}{3}e^{4t} + \frac{8}{3}e^t \end{bmatrix}$$

4. (10 points) Find the projection matrix P for the plane W : 2x + 2y + z = 0 and then find the projection of $\vec{b} = [4, 2, -1]$ on the plane.

Answer: $\vec{b}_W = \underline{\qquad}, P = \underline{\qquad}$. The basis for W are $\left\{ \begin{bmatrix} 1\\0\\-2 \end{bmatrix}, \begin{bmatrix} 0\\1\\-2 \end{bmatrix} \right\}$. For $A = \begin{bmatrix} 1 & 0\\0 & 1\\-2 & -2 \end{bmatrix}$, we have $(A^T A)^{-1} = \begin{bmatrix} 5 & 4\\4 & 5 \end{bmatrix}^{-1} = \frac{1}{9} \begin{bmatrix} 5 & -4\\-4 & 5 \end{bmatrix}$ $P = A(A^T A)^{-1}A^T = \frac{1}{9} \begin{bmatrix} 5 & -4 & -2\\-4 & 5 & -2\\-2 & -2 & 8 \end{bmatrix}$ $\vec{b}_W = P\vec{b} = = \frac{1}{9} \begin{bmatrix} 5 & -4 & -2\\-4 & 5 & -2\\-2 & -2 & 8 \end{bmatrix} \begin{bmatrix} 4\\2\\-1 \end{bmatrix} = \frac{1}{9} \begin{bmatrix} 14\\-4\\-20 \end{bmatrix}$ 5. (10 points) Find the least-square solution of the below system.

$$\begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \\ 1 & -1 & 0 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ -1 \\ -2 \end{bmatrix}$$

Answer: The least-square solution = _____.

Let
$$A = \begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \\ 1 & -1 & 0 \\ 0 & 1 & -1 \end{bmatrix}$$

The given system $A\vec{x} = \vec{b}$, we can rewrite is as $A^T A \vec{x} = A^T \vec{b}$.

$$A^{T}A = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}, A^{T}\vec{b} = \begin{bmatrix} -2 \\ -1 \\ 3 \end{bmatrix},$$

Solve

$$\begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -2 \\ -1 \\ 3 \end{bmatrix}$$

We have the least-square solution is

$$\frac{1}{3} \begin{bmatrix} -2\\ -1\\ 3 \end{bmatrix}$$

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6. (15 points) Use Gram-Schmidt process to find an orthonormal basis for the subspace W of \mathbb{R}^4 spanned by [1, 1, 0, 0], [1, 1, -1, 0], [1, 0, 1, 1] and then use it to find the QR-factorization of A, where

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

Answer : Q=_____, R=_____, an orthonormal basis = $\{\vec{q_1}, \vec{q_2}, \vec{q_3}\}$ By Gram-Schmidt process. Let $\vec{a_1} = [1, 1, 0, 0], \vec{a_2} = [1, 1, -1, 0], \vec{a_3} = [1, 0, 1, 1]$

$$\vec{v}_1 = \vec{a}_1 = [1, 1, 0, 0], \ \vec{q}_1 = \frac{\vec{v}_1}{|\vec{v}_1|} = [\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0, 0]$$
 (1)

$$\vec{v}_2 = \vec{a}_2 - (\vec{a}_2 \cdot \vec{q}_1)\vec{q}_1 = \vec{a}_2 - \sqrt{2}\vec{q}_1 = [0, 0, -1, 0]$$
(2)

$$\vec{q}_2 = \frac{\vec{v}_2}{|\vec{v}_2|} = [0, 0, -1, 0]$$
 (3)

$$\vec{v}_3 = \vec{a}_3 - (\vec{a}_3 \cdot \vec{q}_1)\vec{q}_1 - (\vec{a}_3 \cdot \vec{q}_2)\vec{q}_2 = \vec{a}_3 - \frac{\sqrt{2}}{2}\vec{q}_1 + \vec{q}_2 = \left[\frac{1}{2}, \frac{-1}{2}, 0, 1\right]$$
(4)

$$\vec{q}_3 = \frac{\vec{v}_3}{|\vec{v}_3|} = [\frac{1}{\sqrt{6}}, \frac{-1}{\sqrt{6}}, 0, \frac{2}{\sqrt{6}}]$$
(5)

Then by (1), we get (6). By (2) and (3), we get (7). By (4) and (5), we get (8).

$$\vec{a}_1 = \sqrt{2} \, \vec{q}_1 \Rightarrow \left[\vec{a}_1^T \right] = \left[\vec{q}_1^T \right] \left[\sqrt{2} \right] \tag{6}$$

$$\vec{a}_2 = \sqrt{2}\,\vec{q}_1 + \vec{v}_2 = \sqrt{2}\,\vec{q}_1 + \vec{q}_2 \Rightarrow \begin{bmatrix} \vec{a}_2^T \end{bmatrix} = \begin{bmatrix} \vec{q}_1^T & \vec{q}_2^T \end{bmatrix} \begin{bmatrix} \sqrt{2} \\ 1 \\ 0 \end{bmatrix}$$
(7)

$$\vec{a}_3 = \frac{\sqrt{2}}{2}\vec{q}_1 - \vec{q}_2 + \vec{v}_3 = \frac{\sqrt{2}}{2}\vec{q}_1 - \vec{q}_2 + \frac{\sqrt{3}}{\sqrt{2}}\vec{q}_3 \Rightarrow \begin{bmatrix} \vec{a}_3^T \end{bmatrix} = \begin{bmatrix} \vec{q}_1^T & \vec{q}_2^T & \vec{q}_3^T \end{bmatrix} \begin{bmatrix} \frac{\sqrt{2}}{2} \\ -1 \\ \frac{\sqrt{3}}{\sqrt{2}} \end{bmatrix}$$
(8)

Therefore,

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 1 \end{bmatrix} = QR = \begin{bmatrix} 1/\sqrt{2} & 0 & 1/\sqrt{6} \\ 1/\sqrt{2} & 0 & -1/\sqrt{6} \\ 0 & -1 & 0 \\ 0 & 0 & 2/\sqrt{6} \end{bmatrix} \begin{bmatrix} \sqrt{2} & \sqrt{2} & \frac{\sqrt{2}}{2} \\ 0 & 1 & -1 \\ 0 & 0 & \frac{\sqrt{3}}{\sqrt{2}} \end{bmatrix}$$

7. (10 points) Let W be a subspace of \mathbb{R}^n and let \vec{b} be a vector in \mathbb{R}^n . Prove that there is one and only one vector \vec{p} in W such that $\vec{b} - \vec{p}$ is perpendicular($\underline{\underline{\pi}}$) to every vector in W.

Assume there're two vectors $\vec{p_1}, \vec{p_2} \in W$ such that $\vec{b} - \vec{p_1}$ and $\vec{b} - \vec{p_2}$ are both perpendicular to every vector in W. i.e. $\vec{b} - \vec{p_1}$ and $\vec{b} - \vec{p_2}$ are both in W^{\perp} .

For all vector $\vec{v} \in W$

$$0 = \vec{v} \cdot (\vec{b} - \vec{p_1}) = \vec{v} \cdot \vec{b} - \vec{v} \cdot \vec{p_1} \therefore \vec{v} \cdot \vec{b} = \vec{v} \cdot \vec{p_1}$$
$$0 = \vec{v} \cdot (\vec{b} - \vec{p_2}) = \vec{v} \cdot \vec{b} - \vec{v} \cdot \vec{p_2} \therefore \vec{v} \cdot \vec{b} = \vec{v} \cdot \vec{p_2}$$
$$\therefore \vec{v} \cdot (\vec{p_1} - \vec{p_2}) = 0$$
$$\therefore \vec{p_1} - \vec{p_2} \in W^{\perp}$$

Note that W is a vector space and $\vec{p_1}, \vec{p_2} \in W$, we will have $\vec{p_1} - \vec{p_2} \in W^{\perp}$. Since $\vec{p_1} - \vec{p_2}$ in both W and W^{\perp} , we can easily checked that $\vec{p_1} - \vec{p_2} = \vec{0}$.

8. (10 points) Let A and C be orthogonal $n \times n$ matrices. Show that CAC^{-1} is orthogonal.

A and C be orthogonal matrices, i.e. $A^T A = C^T C = I$. We also know that $C^{-1} = C^T$, i.e. $CAC^{-1} = CAC^T$ $(CAC^T)^T (CAC^T) = (C^T)^T A^T C^T CAC^T = CA^T C^T CAC^T = CA^T (C^T C)AC^T$ $= CA^T IAC^T = C(A^T A)C^T = CIC^T = (C^T C)^T = I^T = I$. We have $CAC^T = CAC^{-1}$ is orthogonal.

- 9. (5 points) Circle True or False. Read each statement in original Greek before answering.
 - (a) **True** False If \vec{v} is an eigenvector of an invertible matrix A, then $c\vec{v}$ is an eigenvector of A^{-1} for all nonzero scalar c. Since $A\vec{v} = \lambda\vec{v}$, we have $A(c\vec{v}) = c(A\vec{v}) = c(\lambda\vec{v}) = \lambda(c\vec{v})$ and $c\vec{v} \neq \vec{0}$ when $\vec{v} \neq \vec{0}$ and c is a nonzero scalar.
 - (b) **True** False Every $n \times n$ real symmetric matrix is real diagonalizable. By Theorem 6.8 from the textbook.
 - (c) True **False** The intersection of W and W^{\perp} is empty. $\vec{0} \in W \cap W^{\perp}$ since $\vec{0}$ belong to every vector space.
 - (d) True False A square matrix is orthogonal if its column vectors are orthogonal.A square matrix is orthogonal if its column vectors are "orthonormal".

For example $\begin{bmatrix} 1\\1 \end{bmatrix}$ and $\begin{bmatrix} 1\\-1 \end{bmatrix}$ are orthogonal. Let $A = \begin{bmatrix} 1 & 1\\1 & -1 \end{bmatrix}$. $A^T A = \begin{bmatrix} 2 & 0\\0 & 2 \end{bmatrix} \neq \begin{bmatrix} 1 & 0\\0 & 1 \end{bmatrix}$

(e) True **False** The least-square solution vector of $A\vec{x} = \vec{b}$ is the projection of \vec{b} on the column space of A.

The least-square solution vector of $A\vec{x} = \vec{b}$ is the vector \vec{y} such that $A\vec{y}$ is the projection of \vec{b} on the column space of A.

學號: _____, 姓名: _____, 以下由閱卷人員填寫

Question:	1	2	3	4	5	6	7	8	9	Total
Points:	10	15	15	10	10	15	10	10	5	100
Score:										