

## 應數一線性代數 2024 春, 期末考 解答

學號: \_\_\_\_\_, 姓名: \_\_\_\_\_

本次考試共有 10 頁 (包含封面), 有 11 題。如有缺頁或漏題, 請立刻告知監考人員。

### 考試須知:

- 請在第一及最後一頁填上姓名學號, 並在每一頁的最上方屬名, 避免釘書針斷裂後考卷遺失。
- 不可翻閱課本或筆記。
- 計算題請寫出計算過程, 閱卷人員會視情況給予部份分數。  
沒有計算過程, 就算回答正確答案也不會得到滿分。  
答卷請清楚乾淨, 儘可能標記或是框出最終答案。

### 高師大校訓: 誠敬宏遠

誠, 一生動念都是誠實端正的。 敬, 就是對知識的認真尊重。  
宏, 開拓視界, 恢宏心胸。 遠, 任重致遠, 不畏艱難。

請尊重自己也尊重其他同學, 考試時請勿東張西望交頭接耳。

1. (10 points) Express  $\frac{z}{w}$  in the form  $a + bi$ , where  $a, b \in \mathbb{R}$ , if

$$z = -1 + i, \quad w = 5 + 4i$$

Answer:  $\frac{z}{w} = \underline{\frac{-1 + 9i}{41}}.$

**Solution :**

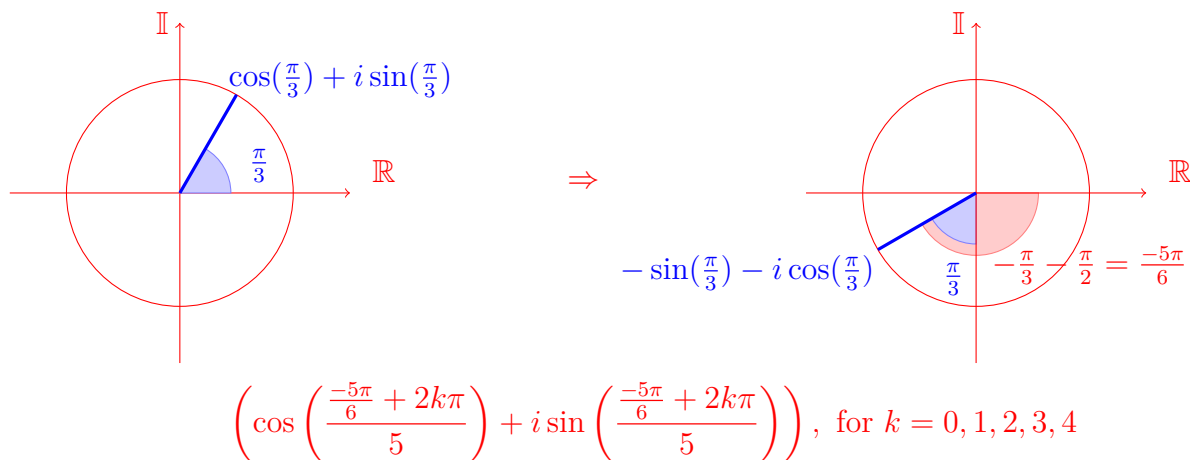
From 9-1. 
$$\frac{z}{w} = \frac{z\bar{w}}{|w|^2}$$

2. (10 points) Find the five fifth roots of  $-\sin(60^\circ) - i \cos(60^\circ)$ . (need not simplify)

Answer:  $\underline{\left( \cos\left(\frac{-\pi}{6} + \frac{2k\pi}{5}\right) + i \sin\left(\frac{-\pi}{6} + \frac{2k\pi}{5}\right) \right), \text{ for } k = 0, 1, 2, 3, 4, \text{ (答案不唯一)}}$

**Solution :**

From 9-1.  $-\sin(60^\circ) - i \cos(30^\circ) = -\sin\left(\frac{\pi}{3}\right) - i \cos\left(\frac{\pi}{3}\right) = \cos\left(\frac{-5\pi}{6}\right) + i \sin\left(\frac{-5\pi}{6}\right).$



3. (10 points) Find an nonzero vector perpendicular to both  $[i, 0, 1 - i]$  and  $[1 + i, 1 - i, 1]$  in  $\mathbb{C}^3$ .

Answer:  $\underline{[-2i, 2 + i, 1 - i], \text{ (答案不唯一)}}$

**Solution :**

$$\begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \vec{i} & \vec{0} & \overline{1-i} \\ \overline{1+i} & \overline{1-i} & \vec{1} \end{vmatrix} = [-2i, 2 + i, 1 - i]$$

4. (10 points) (1) Find the projection matrix  $P$  that project vectors in  $\mathbb{R}^3$  on  $W = sp([-1, 0, 1], [1, 1, -1])$ .  
(2) Given  $\vec{b} = [2, 7, 1]$ , please find the projection  $\vec{b}_W$ .  
(3) If  $\vec{b}_W = \alpha[-1, 0, 1] + \beta[1, 1, -1]$ , find  $\alpha, \beta$ .

Answer:  $P = \frac{1}{2} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{bmatrix}$ ,  $\vec{b}_W = \underline{\frac{1}{2}[1, 14, -1]}$ ,  $\alpha = \underline{13/2}$ ,  $\beta = \underline{7}$ .

**Solution :**

From 6-4.

$$A = \begin{bmatrix} -1 & 1 \\ 0 & 1 \\ 1 & -1 \end{bmatrix}, P = A(A^T A)^{-1} A^T$$

$$\vec{b}_W = P\vec{b}$$

5. (10 points) Find the least-square solution of the below system.

$$\begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \\ 1 & -1 & 0 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ -2 \\ -1 \\ 1 \end{bmatrix}$$

Answer: The least-square solution =  $\frac{1}{3} \begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix}$ .

**Solution :**

From 6-5.

$$A = \begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \\ 1 & -1 & 0 \\ 0 & 1 & -1 \end{bmatrix}$$

$$A\vec{x} = \vec{b} \Rightarrow (A^T A)\vec{x} = A^T \vec{b}$$

$$\Rightarrow \vec{x} = (A^T A)^{-1} A^T \vec{b} = \frac{1}{3} \begin{bmatrix} 1 & -1 & 1 & 0 \\ 1 & 0 & -1 & 1 \\ 1 & 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} 0 \\ -2 \\ -1 \\ 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix}$$

6. (10 points) Let  $V$  be a vector space with ordered bases  $B = \{\vec{b}_1, \vec{b}_2, \vec{b}_3\}$  and  $B' = \{\vec{b}'_1, \vec{b}'_2, \vec{b}'_3\}$ . If

$$C_{B,B'} = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & -2 \\ -1 & 0 & 1 \end{bmatrix}, \text{ and } \vec{v} = 3\vec{b}_1 - 2\vec{b}_2 + \vec{b}_3$$

Find the coordinate vector  $\vec{v}_{B'} = \underline{\begin{bmatrix} -1 \\ -4 \\ -2 \end{bmatrix}}$

**Solution :**

From 7-1.

$$\vec{v} = 3\vec{b}_1 - 2\vec{b}_2 + \vec{b}_3 \Rightarrow \vec{v}_B = \begin{bmatrix} 3 \\ -2 \\ 1 \end{bmatrix}$$

$$\vec{v}_{B'} = C_{B,B'} \vec{v}_B = \begin{bmatrix} -1 \\ -4 \\ -2 \end{bmatrix}$$

7. (10 points) Find the matrix representations  $R_{B,B}$ ,  $R_{B',B'}$  and an invertible  $C$  such that  $R_{B',B'} = C^{-1}R_{B,B}C$  for linear transformation  $T : P_2 \rightarrow P_2$  defined by  $T(p(x)) = \frac{d}{dx}p(x+1)$ ,  $B = (x^2, x, 1)$ ,  $B' = (x^2 - 1, x - 3, 2)$ .

$$C_{B,B'} = \frac{1}{2} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 1 & 3 & 1 \end{bmatrix}, \quad C_{B',B} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & -3 & 2 \end{bmatrix}, \quad R_{B',B'} = \begin{bmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 4 & 1/2 & 0 \end{bmatrix} \quad \text{and}$$

$$R_{B,B} = \begin{bmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 2 & 1 & 0 \end{bmatrix}.$$

Is  $C = C_{B,B'}$  or  $C_{B',B}$ ?  $C_{B',B}$ .

**Solution :**

From 7-2

$$T(x^2) = \frac{d}{dx}(x+1)^2 = 2x+2, \quad T(x) = \frac{d}{dx}(x+1) = 1, \quad T(1) = \frac{d}{dx}1 = 0$$

Thus

$$T\left(\begin{bmatrix} a \\ b \\ c \end{bmatrix}\right) = \begin{bmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 2 & 1 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = R_E \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

We have

$$R_{B,B} = R_B = R_E = \begin{bmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 2 & 1 & 0 \end{bmatrix}$$

By  $C_{B',B} = M_B^{-1}M_{B'} = M_E^{-1}M_{B'} = I^{-1}M_{B'} = M_{B'}$ ,

$$C = C_{B',B} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & -3 & 2 \end{bmatrix}$$

$$C_{B,B'} = C_{B',B}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & -3 & 2 \end{bmatrix}^{-1} = \frac{1}{2} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 1 & 3 & 1 \end{bmatrix}$$

Since

$$R_{B'} = R_{B',B'} = C_{B,B'}R_B C_{B',B}$$

$$R_{B'} = \frac{1}{2} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 1 & 3 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 2 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & -3 & 2 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 4 & 1/2 & 0 \end{bmatrix}$$

8. (10 points) Find an unitary matrix  $U$  and a diagonal matrix  $D$  such that  $D = U^{-1}AU$ . Also find where

$$A = \begin{bmatrix} 2 & 0 & -1+i \\ 0 & -2 & 0 \\ -1-i & 0 & 1 \end{bmatrix}$$

Answer:  $D = \begin{bmatrix} -2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 3 \end{bmatrix}$ ,  $U = \begin{bmatrix} 0 & \frac{1-i}{\sqrt{6}} & \frac{-1+i}{\sqrt{3}} \\ 1 & 0 & 0 \\ 0 & \frac{2}{\sqrt{6}} & \frac{1}{\sqrt{3}} \end{bmatrix}$

### Solution :

From 9-3.

Since  $A$  is Hermitian matrix, it is unitarily diagonalizable.

It is easy to find  $(-2, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix})$ ,  $(0, \begin{bmatrix} 1-i \\ 0 \\ 2 \end{bmatrix})$ ,  $(3, \begin{bmatrix} -1+i \\ 0 \\ 1 \end{bmatrix})$  are three eigenvectors and its corresponding eigenvalues.

1. We also notice that  $\left\langle \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1-i \\ 0 \\ 2 \end{bmatrix} \right\rangle = \left\langle \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1+i \\ 0 \\ 1 \end{bmatrix} \right\rangle = \left\langle \begin{bmatrix} -1+i \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1-i \\ 0 \\ 2 \end{bmatrix} \right\rangle = 0$

or 2. Since  $A$  is Hermitian matrix who has three different eigenvalues, the three eigenvectors must be orthogonal to each other.

$$U = \begin{bmatrix} 0 & \frac{1-i}{\sqrt{6}} & \frac{-1+i}{\sqrt{3}} \\ 1 & 0 & 0 \\ 0 & \frac{2}{\sqrt{6}} & \frac{1}{\sqrt{3}} \end{bmatrix}$$

9. (10 points) Find a Jordan canonical form and a Jordan basis for the matrix  $A$

$$A = \begin{bmatrix} 2 & 0 & 5 & 0 & 0 \\ 0 & 2 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 & -1 \\ 0 & 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix}$$

Answer: Jordan canonical form =  $J = \begin{bmatrix} 2 & 1 & 0 & 0 & 0 \\ 0 & 2 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix}$  ,

Jordan basis =  $\begin{bmatrix} \vec{b}_1 & \vec{b}_2 & \vec{b}_3 & \vec{b}_4 & \vec{b}_5 \end{bmatrix} = \begin{bmatrix} -5 & 0 & 0 & 1 & 0 \\ -1 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix}$  , (不唯一)

**Solution :**

From 9-4 and quiz 16.

$$rref(A - 2I) = \begin{bmatrix} 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}, \text{ null}(A - 2I) = sp(\vec{e}_1, \vec{e}_2, \vec{e}_4)$$

$$rref((A - 2I)^2) = \begin{bmatrix} 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}, \text{ null}((A - 2I)^2) = sp(\vec{e}_1, \vec{e}_2, \vec{e}_3, \vec{e}_4)$$

$$rref((A - 2I)^2) = O, \text{ null}((A - 2I)^2) = \mathbb{C}^5$$

$$\begin{aligned} (A - 2I) : \vec{b}_3 &\rightarrow \vec{b}_2 \rightarrow \vec{b}_1 \rightarrow \vec{0} \\ &\vec{b}_4 \rightarrow \vec{0} \\ &\vec{b}_5 \rightarrow \vec{0} \end{aligned}$$

Notice that  $(\vec{b}_4, \vec{b}_5)$  can be  $(\vec{e}_1, \vec{e}_4)$ ,  $(\vec{e}_2, \vec{e}_4)$  or some other possibility, but not  $(\vec{e}_1, \vec{e}_2)$ .



10. (20 points) Match each matrix with its corresponding properties. Note that each matrix can have multiple properties, and some properties may apply to more than one matrix.

**Properties:** (a) diagonalizable (b) orthogonal diagonalizable (c) unitarily diagonalizable (d) symmetric (e) hermitian (f) normal (g) has reduced row-echelon form (h) has jordan canonical form

(i)  $\begin{bmatrix} 2 & 3 & 0 & 1 & -1 \\ 3 & 0 & -2 & 5 & 1 \end{bmatrix}$ . Answer: (i) is a matrix: g

(ii)  $\begin{bmatrix} 5 & -1 & -2 \\ 1 & 3 & -2 \\ -1 & -1 & 4 \end{bmatrix}$ . Answer:  $\det(ii) = (2 - \lambda)(4 - \lambda)(6 - \lambda)$ , not symmetric, not normal: agh

(iii)  $\begin{bmatrix} 1 & 1+i & 0 \\ 1-i & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$ . Answer: (iii) is a hermitian and not symmetric: acefgh

(iv)  $\begin{bmatrix} 1 & 2 & 6 \\ 2 & 0 & -4 \\ 6 & -4 & 3 \end{bmatrix}$ . Answer: (iv) is a real symmetric: abcdefgh

**Solution :**

p.s. (iv) 跟期中考第二題一模一樣。

p.s.2. 考試的時候提醒過了，沒給理由沒分。

(a) **(Thm 5.4)**  $A$  is diagonalizable iff the a.m. = g.m. for each eigenvalue of  $A$ .

(b) **(Def in p.354)**  $A$  is orthogonal diagonalizable: 1.  $A$  is diagonalizable. 2. needs to check the eigenspaces are orthogonal.

(1) **(6.3 #24)** If  $A$  is orthogonal diagonalizable then  $A$  is symmetric.

(c) **(Thm 9.7)**  $A$  is unitarily diagonalizable iff  $A$  is normal.

(d) **(Def 1.11)**  $A$  is symmetric if  $A^T = A$ .

(1) **(Thm 6.8)** If  $A$  is real symmetric then  $A$  is orthogonal diagonalizable.

(2) **(9.3 #19(h))** If  $A$  is real symmetric then  $A$  is normal.

(e) **(Def 9.4)**  $A$  is hermitian if  $A^* = A$ .

(1) **(9.2 #43(a))** If  $A$  hermitian then  $A$  is normal.

(f) **(Def 9.5)**  $A$  is normal if  $AA^* = A^*A$ .

(g) **(Def in p.63)**  $A$  has reduced row-echelon form if  $A$  is a matrix.

(h) **(Thm 9.9)**  $A$  has jordan canonical form if  $A$  is a square matrix.

